

SMARC T335X SDK7

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Building TI/Embedian's Arago SDK 7.0 Distribution

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Introduction

This document describes how Embedian builds a customized version of TI's am335x AMSDK 7.0 release for Embedian's SMARC T335X product platform. The approach is to pull from Embedian's public facing GIT repository and build that using bitbake. The reason why we use this approach is that it allows co-development. The build output is comprised of binary images, feed packages, and an SDK for SMARC T335X specific development.

TI makes their AMSDK Arago build scripts available via the following GIT repository:

```
http://arago-project.org/git/projects/oe-layerssetup.git
```

If you're interested in TI's overall EZSDK build and test process you should analyze the following repository:

```
http://arago-project.org/git/projects/tisdk-build-scripts.git
```

It is this repository that actually pulls in the `oe-layerssetup` project to perform the Linux AMSDK builds for TI's entire suite of ARM CortexA chips. In this document we are only concerned with the `oe-layerssetup` project.

Overview of the meta-embedian-SDK7 Yocto Layer

The supplied meta-embedian-sdk7 Yocto compliant layer has the following organization:

```
.
|-- conf
|   |-- layer.conf
|   |-- site.conf
|   |-- machine
|   |   |-- smarct335x.conf
|-- README
|-- recipes-bsp
|   |-- u-boot
|   |   |-- u-boot_2014.04-smarct335x.bb
|   |   |-- u-boot_2013.10-smarct335x.bb
|-- recipes-connectivity
|   |-- lftp
|   |   |-- lftp_4.0.5.bb
|-- recipes-core
|   |-- base-files
|   |   |-- base-files_3.0.14.bbappend
|   |-- busybox
|   |   |-- busybox_1.20.2.bbappend
|   |   |   |-- busybox
|   |   |   |   |-- defconfig
|-- images
|   |-- arago-base-smarct335x-image.bb
|   |-- arago-image.inc
|   |-- meta-toolchain-smarc-tisdk.bb
|   |-- smarct335x-initramfs-image.bb
|   |-- smarct335x-rootfs-image.bb
|-- init-ifupdown
|   |-- init-ifupdown_1.0.bbappend
|   |   |-- init-ifupdown
|   |   |   |-- interfaces
|-- initscripts
|   |-- initscripts_1.0.bbappend
|-- packagegroups
|   |-- packagegroup-arago-smarct335x-base.bb
|   |-- packagegroup-arago-smarct335x-console.bb
|   |-- packagegroup-arago-smarct335x-matrix.bb
|   |-- packagegroup-arago-smarct335x-sdk.bb
|   |-- packagegroup-initramfs-boot.bb
|-- recipes-devtools
|   |-- nodejs
|   |   |-- nodejs_0.10.11.bb
|   |   |-- nodejs_0.10.17.bb
|   |   |-- nodejs_0.10.4.bb
|   |   |-- nodejs_0.8.14.bb
|   |   |-- nodejs_0.8.21.bb
|   |-- ltp-ddt
|   |   |-- ltp-ddt_0.0.4.bbappend
|   |   |-- ltp-ddt
|   |   |   |-- 0001-add-smarct335x-platform-support.patch
|-- pinmux-utility
|   |-- pinmux-utility_2.5.2.0.bbappend
|-- recipes-kernel
|   |-- linux
|   |   |-- linux.inc
|   |   |-- linux-dtb.inc
|   |   |-- copy-defconfig.inc
|   |   |-- setup-defconfig.inc
|   |   |-- linux-smarct335x-3.2
|   |   |   |-- defconfig
|   |   |-- linux-smarct335x_3.2.bb
|   |   |-- linux-smarct335x-staging_3.12.bb
|   |   |-- linux-smarct335x-staging
|   |   |   |-- defconfig
|-- cryptodev
|   |-- cryptodev_1.6.bbappend
```

```

|-- recipes-multimedia
|   |-- amsdk-av-files
|       |-- amsdk-av-files_1.1.bbappend
|   |-- x264
|       |-- x264_git.bbappend
|-- recipes-support
|   |-- boost
|       |-- boost_1.53.0.bb
|       |-- boost.inc
|       |-- files
|   |-- ntp
|       |-- files
|       |-- ntp_4.2.6p5.bb
|       |-- ntp.inc
|-- recipes-tisdk
    |-- ti-tisdk-makefile
        |-- ti-tisdk-makefile_1.0.bbappend

```

Notes on *meta-embedian-sdk7* layer content

[conf/machine/*](#)

This folder contains the machine definitions for the **smarct335x** platform and backup repository in Embedian. These select the associated kernel, kernel config, u-boot, u-boot config, and UBI image settings.

[recipes-bsp/u-boot/*](#)

This folder contains recipes used to build DAS U-boot for **smarct335x** platform.

[recipes-connectivity/lftp/*](#)

This folder adds lftp ftp client utility for **smarct335x** platform.

[recipes-core/base-files/*](#)

This recipe is used to amend the device hostname for the platform.

[recipes-core/busybox/*](#)

This recipe modifies TI's BusyBox configuration to remove telnet from the image.

[recipes-core/images/*](#)

These recipes are used to create the final target images for the devices. When you run Bitbake one of these recipes would be specified. For example, to build the root file system for the **smarct335x** platform:

```
MACHINE=smarct335x bitbake -k smarct335x-rootfs-image
```

[recipes-core/init-ifupdown*](#)

This recipe is used to amend device network interfaces

[recipes-devtools/nodejs/*](#)

These recipes build the Node.js Javascript server execution environment.

[recipes-kernel/linux/*](#)

Contains the recipes needed to build the **smarct335x** Linux kernels.

[recipes-multimedia/amsdk-av-files/*](#)

This recipe is to add smarct335x compatible machine for the platform.

[recipes-multimedia/x264/*](#)

This original commit history has been rewritten.

[recipes-support/boost/*](#)

Adds Boost to the images. Boost provides various C++ libraries that encourage cross-platform development.

[recipes-support/ntp/*](#)

Network time protocol support.

[recipes-tisdk/ti-tisdk-makefile/*](#)

Add smarct335x device tree into Makefile.

Setting Up the Tools and Build Environment

To build the latest TI am335x 7.0 AMSDK you first need an Ubuntu Linux 12.04 LTS or Ubuntu 14.04 LTS installation (preferably 32bit). Since bitbake does not accept building images using root privileges, please **do not** login as a root user when performing the instructions in this section.

Once you have Ubuntu 12.04 LTS or Ubuntu 14.04 LTS running, install the additional required support packages using the following console command:

```
$ sudo apt-get install gawk wget git-core diffstat unzip texinfo build-essential chrpath libsdl1.2-dev xterm python-m2crypto bc
```

If you are using a 64-bit Linux, then you'd also need to install 32-bit support libraries, needed by the pre-built Linaro toolchain and other binary tools.

```
$ sudo dpkg --add-architecture i386 && sudo apt-get update && sudo apt-get install lib32ncurses5
```

You'll also need to change the default shell to `bash` from Ubuntu's default `dash` shell (select the <No> option):

```
$ sudo dpkg-reconfigure dash
```

To build TI's am335x SDK you will need to install the Linaro arm compiler that TI used for the release:

```
$ wget http://releases.linaro.org/archive/13.04/components/toolchain/binaries/gcc-linaro-arm-linux-gnueabi-4.7-2013.04-20130415_linux.tar.xz
$ sudo tar -C /opt -xJf gcc-linaro-arm-linux-gnueabi-4.7-2013.04-20130415_linux.tar.xz
```

Add the following PATH definition to the `.bashrc` file in your `$HOME` directory:

```
export PATH=/opt/gcc-linaro-arm-linux-gnueabi-4.7-2013.04-20130415_linux/bin:$PATH
```

Next clone and initialize TI's am335x SDK build process:

```
$ git clone http://arago-project.org/git/projects/oe-layersetup.git oe-layersetup-smarct33-sdk7
$ cd oe-layersetup-smarct33-sdk7
$ git checkout -b tisdk-07-01 72ea335f3879a8752d7dfc7f25d68913b222f867
$ ./oe-layertool-setup.sh -f configs/amsk/amsk-07.01.00.00-config.txt
```



Update (2015-12-07)

Some repo locations of QT demo application has been moved by TI. You need to apply the other patch (0001-sdk7-fix-repo-location.patch)

If your host machine is Ubuntu14.04, you need an additional patch (fix-binutils-textinfo-ubuntu14.04.patch) to build AMSDK7 rootfs (You do not need to apply this patch if built in Ubuntu 12.04 LTS).

```
$ cd ~/oe-layersetup-smarct33-sdk7/source/meta-arago/
```

```
$ wget -c http://developer.embedian.com/download/attachments/8847362/fix-binutils-textinfo-ubuntu14.04.patch
$ patch -p1 <fix-binutils-textinfo-ubuntu14.04.patch
$ wget -c http://developer.embedian.com/download/attachments/8847362/0001-sdk7-fix-repo-location.patch
$ patch -p1 <0001-sdk7-fix-repo-location.patch
$ rm fix-binutils-textinfo-ubuntu14.04.patch 0001-sdk7-fix-repo-location.patch
```

Add the Embedian's `meta-embedian-sdk7` layer to the build process.

```
$ cd ~/oe-layersetup-smarct33-sdk7/sources
$ git clone git@git.embedian.com:developer/meta-embedian-sdk7.git
$ cd ~/oe-layersetup-sdk7/build
```

Edit the `~/oe-layersetup-sdk7/build/conf/bblayers.conf` file to include the `meta-embedian-sdk7` layer in the layer list. It should look something like this (the example reflects the absolute paths on my machine):

```
# This template file was created by taking the oe-core/meta/conf/bblayers.conf
# file and removing the BBLAYERS section at the end.

# LAYER_CONF_VERSION is increased each time build/conf/bblayers.conf
# changes incompatibly
LCONF_VERSION = "5"

BBPATH = "${TOPDIR}"
BBFILES ?= ""

# Layers configured by oe-core-setup script
BBLAYERS += " \
/home/oeeric/oe-layersetup-sdk7/sources/meta-embedian-sdk7 \
/home/oeeric/oe-layersetup-sdk7/sources/meta-arago/meta-arago-distro \
/home/oeeric/oe-layersetup-sdk7/sources/meta-arago/meta-arago-extras \
/home/oeeric/oe-layersetup-sdk7/sources/meta-qt5 \
/home/oeeric/oe-layersetup-sdk7/sources/meta-openembedded/toolchain-layer \
/home/oeeric/oe-layersetup-sdk7/sources/meta-openembedded/meta-networking \
/home/oeeric/oe-layersetup-sdk7/sources/meta-openembedded/meta-oe \
/home/oeeric/oe-layersetup-sdk7/sources/meta-ti \
/home/oeeric/oe-layersetup-sdk7/sources/meta-linaro/meta-linaro-toolchain \
/home/oeeric/oe-layersetup-sdk7/sources/oe-core/meta \
"
```



Note:

If your platform is SMARC T3354 (with `sgx` features), you can simply add "`sgx`" in the `MACHINE_FEATURES` to have the `powervr` driver loaded by editing the `~/oe-layersetup-sdk7/source/meta-embedian/conf/machine/smarct335x.conf` file. Find `MACHINE_FEATURES` and add "`sgx`" in the very bottom:

```
MACHINE_FEATURES = "kernel26 alsa usb gadget usbhost apm vfat ext2 screen touchscreen ethernet sgx"
```

Please do not enable the `sgx` `MACHINE_FEATURES` if your platform is SMARC T3352.

Building the target platforms

To build the Embedian SMARC T335X and am335x-evm developer board images, respectively, use the following commands:

```
$ cd ~/oe-layersetup-sdk7/build
$ source conf/setenv
$ MACHINE=smarct335x bitbake -k smarct335x-rootfs-image
```



Note

The first clean build might take more than 10 hours. If you met errors during the building process, let it finish and usually build again should be fine.

Once it done, you can find all required images under `~/oe-layersetup-sdk7/build/arago-tmp-external-linaro-toolchain/deploy/images/`

You may want to build programs that aren't installed into a root file system so you can make them available via a feed site (described below.) To do this you can build the package directly and then build the package named `package-index` to add the new package to the feed site.

The following example builds the `minicom` program and makes it available on the feed site:

```
$ MACHINE=smarct335x bitbake minicom
$ MACHINE=smarct335x bitbake package-index
```

Once the build(s) are completed you'll find the resulting images, feeds and licenses in folder `~/oe-layersetup-sdk7/build/arago-tmp-external-linaro-toolchain/deploy`.

`deploy/images/*`

This folder contains the binary images for the root file system and the Embedian SMARCT335X specific version of the am335x SDK. Specifically the images are:

`deploy/images/u-boot.img`

This u-boot bootloader binary for SMARC T335X

`deploy/images/MLO`

The "Stage 1 Boot Loader" for SMARC T335X. Its purpose is load the Stage 2 Boot Loader (u-boot.img).

`deploy/images/zImage`

The kernel zImage for SMARC T335X.

`deploy/images/zImage-am335x-smarct335x.dtb`

The device tree binary file for SMARC T335X.

`deploy/images/smarct335x-rootfs-image-smarct335x*`

Embedian root file system images for software development on Embedian's SMARC T335X platforms.

`deploy/images/smarct335x-amsdk-image*`

These files contain the entire TI AMSDK augmented with Boost and other options to simplify Embedian SMARC T335X software development.

`deploy/images/arago-base-tisdk-image-smarct335x*`

These images are used to create the SMARC T335X AMSDK (see `smarct335x-amsdk-image-smarct335x*`).

`deploy/images/tisdk-rootfs-image-am335x-evm*`

TI Arago root file system images for software development on TI's am335x-evm and BeagleBone platforms.

deploy/ipk/*

This folder contains all the packages used to construct the root file system images. They are in **opkg** format (similar format to Debian packages) and can be dynamically installed on the target platform via a properly constructed *feed* file. Here is an example of the feed file (named [arago-smarct335x-feed.conf](#)) that is used internally at Embedian to install upgrades onto a **smarct335x** platform without reflashing the file system:

```
src/gz smarct335x http://www.embedian.com/arago-sdk7/smarct335x
src/gz cortexa8hf-vfp-neon-3.8 http://www.embedian.com/arago-sdk7/cortexa8hf-vfp-neon-3.8
src/gz all http://www.embedian.com/arago-sdk7/all
```

deploy/licenses/*

A database of all licenses used in all packages built for the system.

deploy/sdk/arago-2013.12-cortexa8-linux-gnueabi-tisdk.sh

The installer for ARM toolchain that was created for the target platform. In Embedian's case that means that the headers for the Boost libraries are baked into the tools. (Generate by meta-toolchain-smarc-tisdk image)

Setup SD Card

For these instructions, we are assuming: DISK=/dev/mmcblk0, "lsblk" is very useful for determining the device id.

```
$ export DISK=/dev/mmcblk0
```

Erase SD card:

```
$ sudo dd if=/dev/zero of=${DISK} bs=1M count=16
```

Create Partition Layout:

With util-linux v2.26, sfdisk was rewritten and is now based on libfdisk.

```
sfdisk
$ sudo sfdisk --version
sfdisk from util-linux 2.27.1
```

Create Partitions:

```
i sfdisk >=2.26.x
$ sudo sfdisk ${DISK} <<-__EOF__
1M,48M,0xE,*
'''-
__EOF__
```

```
i sfdisk <=2.25
$ sudo sfdisk --in-order --Linux --unit M ${DISK} <<-__EOF__
1,48,0xE,*
'''-
__EOF__
```

Format Partitions:

```
for: DISK=/dev/mmcblk0
$ sudo mkfs.vfat -F 16 ${DISK}p1 -n boot
$ sudo mkfs.ext4 ${DISK}p2 -L rootfs
```

```
for: DISK=/dev/sdX
$ sudo mkfs.vfat -F 16 ${DISK}1 -n boot
$ sudo mkfs.ext4 ${DISK}2 -L rootfs
```

Mount Partitions:

On some systems, these partitions may be auto-mounted...

```
$ sudo mkdir -p /media/boot/dtbs
$ sudo mkdir -p /media/rootfs/

for: DISK=/dev/mmcblk0
$ sudo mount ${DISK}p1 /media/boot/
$ sudo mount ${DISK}p2 /media/rootfs/

for: DISK=/dev/sdX
$ sudo mount ${DISK}1 /media/boot/
$ sudo mount ${DISK}2 /media/rootfs/
```

Install Bootloader

Copy MLO/u-boot.img to the boot partition

deploy/images

```
$ sudo cp -v MLO /media/boot/
$ sudo cp -v u-boot.img /media/boot/
```

uEnv.txt based bootscript

Create "uEnv.txt" boot script: (vim uEnv.txt)

For 3.12.y or after :

~/uEnv.txt

```
optargs="consoleblank=0 mem=512M"
#u-boot eMMC specific overrides; Angstrom Distribution (SMARC T335X) 2014-05-20
kernel_file=zImage
initrd_file=initrd.img

loadaddr=0x82000000
initrd_addr=0x88080000
fdtaddr=0x88000000
fdtfile=am335x-smarct335x.dtb

initrd_high=0xffffffff
fdt_high=0xffffffff

loadimage=load mmc ${mmcdev}:${mmcpart} ${loadaddr} ${kernel_file}
loadinitrd=load mmc ${mmcdev}:${mmcpart} ${initrd_addr} ${initrd_file}; setenv initrd_size ${filesize}
loadfdt=load mmc ${mmcdev}:${mmcpart} ${fdtaddr} /dtbs/${fdtfile}
#

##Un-comment to enable systemd in Debian Wheezy
#optargs=quiet init=/lib/systemd/systemd

console=ttyO3,115200n8
mmcroot=/dev/mmcblk1p2 ro
mmcrootfstype=ext4 rootwait fixrtc

mmccargs=setenv bootargs console=${console} root=${mmcroot} rootfstype=${mmcrootfstype} ${optargs}

#zImage:
uenvcmd=run loadimage; run loadfdt; run mmccargs; bootz ${loadaddr} - ${fdtaddr}

#zImage + ulnitrd: where ulnitrd has to be generated on the running system.
```

```
#boot_fdt=run loadimage; run loadinitrd; run loadfdt
#uenvcmd=run boot_fdt; run mmcargs; bootz ${loadaddr} ${initrd_addr}:${initrd_size} ${fdtaddr}

###Begin Rootfs from NFS
#serverip=192.168.1.51
#rootpath=/srv/nfs/smarct335x/ubuntu1204/
#nfsOpts=nolock,acdirmin=60
#netargs=setenv bootargs console=${console} ${optargs} root=/dev/nfs nfsroot=${serverip}:${rootpath},${nfsOpts} rw ip=dhcp
##netboot=echo Loading kernel from SDCARD and booting from NFS ...; run loadimage; run netargs; bootz ${loadaddr} - ${fdtaddr}
##uenvcmd=run netboot
###End Rootfs from NFS

###Begin Load kernel from TFTP
#netmask=255.255.255.0
#ipaddr=192.168.1.65
#serverip=192.168.1.51
#netboot=echo Loading kernel and device tree from TFTP and booting from NFS ...; setenv autoload no; tftp ${loadaddr} ${kernel_file}; tftp
${fdtaddr} ${fdtfile}; run netargs; bootz ${loadaddr} - ${fdtaddr}
#uenvcmd=run netboot
###End Load kernel from TFTP
```

Copy uEnv.txt to the boot partition:

```
~/
$ sudo cp -v ./uEnv.txt /media/boot/
```

Install Kernel zImage

Copy zImage to the boot partition:

```
deploy/images
$ sudo cp -v zImage /media/boot
```

Install Kernel Device Tree Binary

Copy device tree binary to /media/boot/dtbs (Note: the file name in /media/boot/dtbs/ has to be am335x-smarct335x.dtb)

```
$ sudo cp -v zImage-am335x-smarct335x.dtb /media/boot/dtbs/am335x-smarct335x.dtb
```

Install Root File System and Kernel Modules

Install Root File System

Copy Root File System:

Arago:

```
deploy/images
$ sudo tar xvfz smarct335x-rootfs-image-smarct335x.tar.gz -C /media/rootfs
```

Note:

Kernel modules are included in root file systems.

The following procedure can be used on a Embedian SMARC T335X device to download and utilize the feed file show above to install the `minicom` terminal emulation program:

```
# cd /etc/opkg
# wget http://www.embedian.com/feedfiles-sdk7/arago-smarct335x-feed.conf
# opkg update
# opkg upgrade
# opkg install minicom
```

Writing Bitbake Recipes

In order to package your application and include it in the root filesystem image, you must write a BitBake recipe for it.

When starting from scratch, it is easiest to learn by example from existing recipes.

Example HelloWorld recipe using autotools

For software that uses autotools (`./configure`; `make`; `make install`), writing recipes can be very simple:

```
DESCRIPTION = "Hello World Recipe using autotools"
HOMEPAGE = "http://www.embedian.com/"
SECTION = "console/utils"
PRIORITY = "optional"
LICENSE = "GPL"
PR = "r0"

SRC_URI =
"git://git@git.embedian.com/developer/helloworld-autotools.git;protocol=ssh;tag=v1.0"
S = "${WORKDIR}/git"

inherit autotools
```

`SRC_URI` specifies the location to download the source from. It can take the form of any standard URL using `http://`, `ftp://`, etc. It can also fetch from SCM systems, such as `git` in the example above.

`PR` is the package revision variable. Any time a recipe is updated that should require the package to be rebuilt, this variable should be incremented.

`inherit autotools` brings in support for the package to be built using autotools, and thus no other instructions on how to compile and install the software are needed unless something needs to be customized.

`S` is the source directory variable. This specifies where the source code will exist after it is fetched from `SRC_URI` and unpacked. The default value is `${WORKDIR}/${PN}-${PV}`, where `PN` is the package name and `PV` is the package version. Both `PN` and `PV` are set by default using the filename of the recipe, where the filename has the format `PN_PV.bb`.

Example HelloWorld recipe using a single source file

This example shows a simple case of building a `helloworld.c` file directly using the default compiler (`gcc`). Since it isn't using autotools or `make`, we have to tell BitBake how to build it explicitly.

```

DESCRIPTION = "HelloWorld"
SECTION = "examples"
LICENSE = "GPL"

SRC_URI = "file://helloworld.c"

S = "${WORKDIR}"

do_compile() {
    ${CC} ${CFLAGS} ${LDFLAGS} helloworld.c -o helloworld
}

do_install() {
    install -d ${D}${bindir}
    install -m 0755 helloworld ${D}${bindir}
}

```

In this case, `SRC_URI` specifies a file that must exist locally with the recipe. Since there is no code to download and unpack, we set `S` to `WORKDIR` since that is where `helloworld.c` will be copied to before it is built.

`WORKDIR` is located at `${OETREE}/build/arago-tmp-external-linaro-toolchain/work/armv7ahf-vfp-neon-3.8-oe-linux-gnueabi/<package name and version>` for most packages. If the package is machine-specific (rather than generic for the `armv7ahf` architecture), it may be located in the `smarct335x-oe-linux-gnueabi` subdirectory depending on your hardware (this applies to kernel packages, images, etc).

`do_compile` defines how to compile the source. In this case, we just call `gcc` directly. If it isn't defined, `do_compile` runs `make` in the source directory by default.

`do_install` defines how to install the application. This example runs `install` to create a `bin` directory where the application will be copied to and then copies the application there with permissions set to 755.

`D` is the destination directory where the application is installed to before it is packaged.

`${bindir}` is the directory where most binary applications are installed, typically `/usr/bin`.

For a more in-depth explanation of BitBake recipes, syntax, and variables, see the [Recipe Chapter](#) of the OpenEmbedded User Manual.

Setup eMMC

Setting up eMMC usually is the last step at development stage after the development work is done at your SD card or NFS environments. eMMC on module will be always emulated as `/dev/mmcblk0`. Setting up eMMC now is nothing but changing the device descriptor.

This section gives a step-by-step procedure to setup eMMC flash. Users can write a shell script your own at production to simplify the steps.

First, we need to backup the final firmware from your SD card or NFS.

Prepare for eMMC binaries from SD card (or NFS):

Insert SD card into your Linux PC. For these instructions, we are assuming: `DISK=/dev/mmcblk0`, "`lsblk`" is very useful for determining the device id.

For these instruction, we are assuming: `DISK=/dev/mmcblk0`, "`lsblk`" is very useful for determining the device id.

```
$ export DISK=/dev/mmcblk0
```

Mount Partitions:

On some systems, these partitions may be auto-mounted...

```
$ sudo mkdir -p /media/boot/
$ sudo mkdir -p /media/rootfs/

for : DISK=/dev/mmcblk0
$ sudo mount ${DISK}p1 /media/boot/
$ sudo mount ${DISK}p2 /media/rootfs/

for : DISK=/dev/sdX
$ sudo mount ${DISK}1 /media/boot/
$ sudo mount ${DISK}2 /media/rootfs/
```

Copy MLO to rootfs partition:

```
$ sudo cp -v /media/boot/MLO /media/rootfs/home/root
```

Copy u-boot.img to rootfs partition:

```
$ sudo cp -v /media/boot/u-boot.img /media/rootfs/home/root
```

Copy initramfs zImage to rootfs partition:

```
arago-tmp-external-linaro-toolchain/deploy/images
$ sudo cp -v zImage /media/rootfs/home/root
```

Copy uEnv.txt to rootfs partition:

Copy and paste the following contents to /media/rootfs/home/root (\$ sudo vim /media/rootfs/home/root/uEnv.txt)

For kernel v3.12.y+:

```
optargs="consoleblank=0 mem=512M"
#u-boot eMMC specific overrides; Angstrom Distribution (SMARC T335X) 2014-05-20
kernel_file=zImage
initrd_file=initrd.img

loadaddr=0x82000000
initrd_addr=0x88080000
fdtaddr=0x88000000
fdtfile=am335x-smarct335x.dtb

initrd_high=0xffffffff
fdt_high=0xffffffff

loadimage=load mmc ${mmcdev}:${mmcpart} ${loadaddr} ${kernel_file}
loadinitrd=load mmc ${mmcdev}:${mmcpart} ${initrd_addr} ${initrd_file}; setenv initrd_size ${filesize}
loadfdt=load mmc ${mmcdev}:${mmcpart} ${fdtaddr} /dtbs/${fdtfile}
#

##Un-comment to enable systemd in Debian Wheezy
#optargs=quiet init=/lib/systemd/systemd

console=ttyO3,115200n8
mmcroot=/dev/mmcblk0p2 ro
mmcrootfstype=ext4 rootwait fixrtc

mmcargs=setenv bootargs console=${console} root=${mmcroot} rootfstype=${mmcrootfstype} ${optargs}

#zImage:
uenvcmd=run loadimage; run loadfdt; run mmcargs; bootz ${loadaddr} - ${fdtaddr}

#zImage + ulnitrd: where ulnitrd has to be generated on the running system.
#boot_fdt=run loadimage; run loadinitrd; run loadfdt
#uenvcmd=run boot_fdt; run mmcargs; bootz ${loadaddr} ${initrd_addr}:${initrd_size} ${fdtaddr}
```

```

###Begin Rootfs from NFS
#serverip=192.168.1.51
#rootpath=/srv/nfs/smarct335x/ubuntu1204/
#nfsopts=nolock,acdirmin=60
#netargs=setenv bootargs console=${console} ${optargs} root=/dev/nfs nfsroot=${serverip}:${rootpath},${nfsopts} rw ip=dhcp
##netboot=echo Loading kernel from SDCARD and booting from NFS ...; run loadimage; run netargs; bootz ${loadaddr} - ${fdtaddr}
##uenvcmd=run netboot
###End Rootfs from NFS

###Begin Load kernel from TFTP
#netmask=255.255.255.0
#ipaddr=192.168.1.65
#serverip=192.168.1.51
#netboot=echo Loading kernel and device tree from TFTP and booting from NFS ...; setenv autoload no; tftp ${loadaddr} ${kernel_file}; tftp
${fdtaddr} ${fdtfile}; run netargs; bootz ${loadaddr} - ${fdtaddr}
#uenvcmd=run netboot
###End Load kernel from TFTP

```

Copy real rootfs to rootfs partition:

```

$ pushd /media/rootfs

$ sudo tar cvfz ~/smarct335x-emmc-rootfs.tar.gz .

$ sudo mv ~/smarct335x-emmc-rootfs.tar.gz /media/rootfs/home/root

$ popd

```

Remove SD card:

```

$ sync
$ sudo umount /media/boot
$ sudo umount /media/rootfs

```

Insert this SD card into your SMARC T335X device.

Now it will be almost the same as you did when setup your SD card, but the eMMC device descriptor is /dev/mmcblk1 now.

```

$ export DISK=/dev/mmcblk0

```

Erase SD card:

```

$ sudo dd if=/dev/zero of=${DISK} bs=1M count=16

```

Create Partition Layout:

```

$ sudo sfdisk --in-order --Linux --unit M ${DISK} <<-__EOF__
1,48,0xE,*
',',-
__EOF__

```

Format Partitions:

```

$ sudo mkfs.vfat -F 16 ${DISK}p1 -n boot
$ sudo mkfs.ext4 ${DISK}p2 -L rootfs

```

Mount Partitions:

```
$ sudo mkdir -p /media/boot/  
$ sudo mkdir -p /media/rootfs/  
$ sudo mount ${DISK}p1 /media/boot/  
$ sudo mount ${DISK}p2 /media/rootfs/
```

Install binaries for partition 1

Copy MLO/u-boot.img/uEnv.txt/zImage to the boot partition

```
$ sudo cp -v MLO u-boot.img zImage uEnv.txt /media/boot/
```

Install Kernel Device Tree Binary

```
$ sudo mkdir -p /media/boot/dtbs  
$ sudo cp -v am335x-smarct335x.dtb /media/boot/dtbs
```

Install Root File System

```
$ sudo tar -zxvf smarct335x-emmc-rootfs.tar.gz -C /media/rootfs
```

Unmount eMMC:

```
$ sync  
$ sudo umount /media/boot  
$ sudo umount /media/rootfs
```

Switch your Boot Select to eMMC and you will be able to boot up from eMMC now.

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